

Uncertainty Quantification in Machine Learning

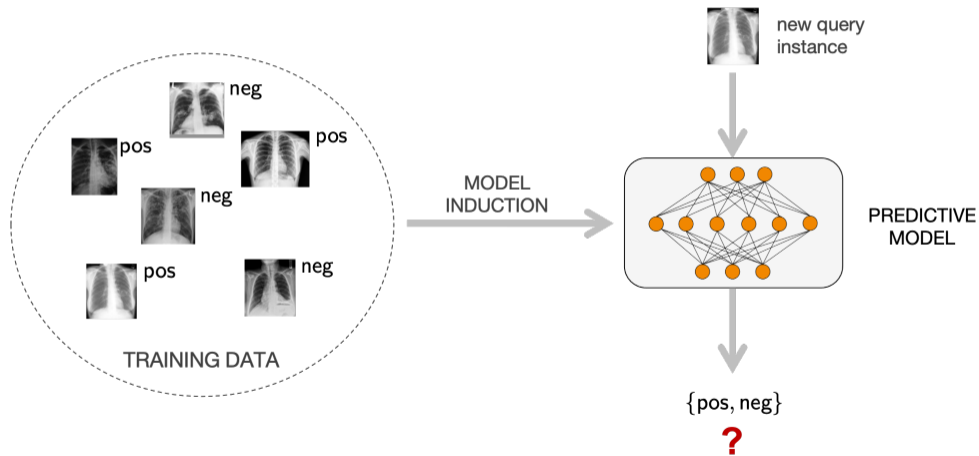
From Aleatoric to Epistemic

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COPA 2022, Brighton, UK, August 24, 2022

Need for uncertainty-awareness of ML systems

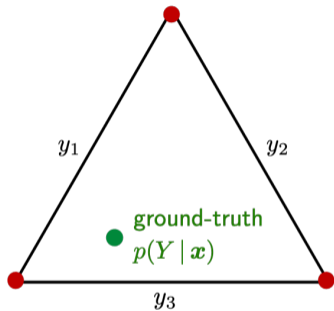


Lack of uncertainty-awareness of ML systems

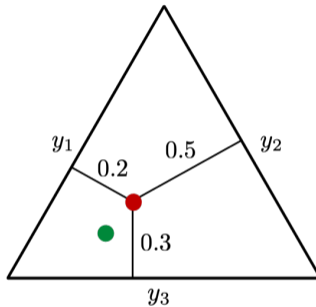
- Predictions by EfficientNet on test images from ImageNet: For the left image, the neural network predicts “typewriter keyboard” with certainty 83.14 %, for the right image “stone wall” with certainty 87.63 %.



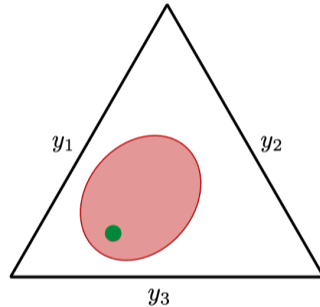
Uncertainty representation and levels of uncertainty-awareness



Deterministic predictor
 $h : \mathcal{X} \rightarrow \mathcal{Y}$

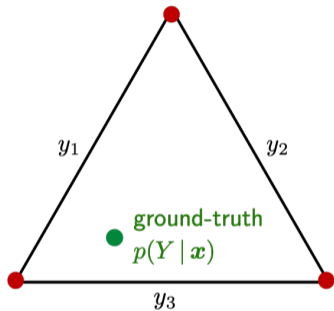


Probabilistic predictor
 $h : \mathcal{X} \rightarrow \mathbb{P}(\mathcal{Y})$

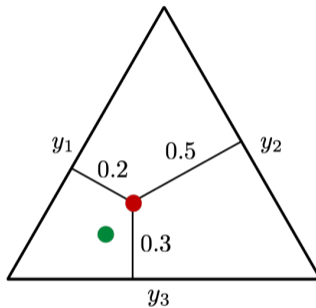


Credal predictor
 $h : \mathcal{X} \rightarrow \mathbb{Q}(\mathbb{P}(\mathcal{Y}))$

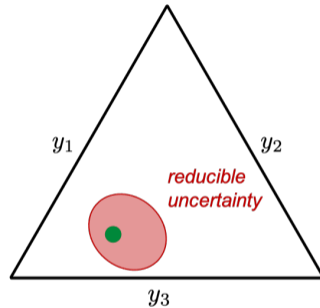
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Aleatoric versus epistemic uncertainty

■ **Aleatoric** (aka statistical) uncertainty

- ▶ refers to the notion of **randomness**, that is, the variability in the outcome which is due to inherently random effects,
- ▶ is a property of the **data-generating process**,
- ▶ and as such **irreducible**.

Aleatoric versus epistemic uncertainty

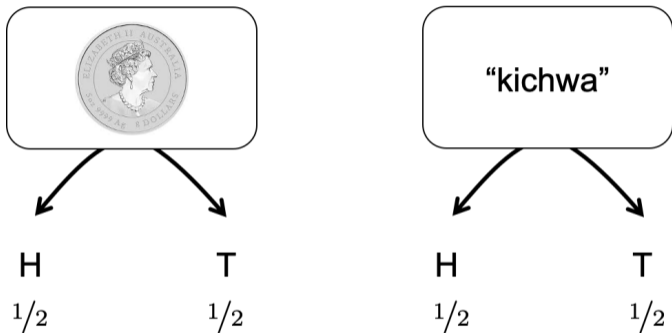
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■ Epistemic (aka systematic) uncertainty

- ▶ refers to uncertainty caused by a **lack of knowledge**, i.e.,
- ▶ to the epistemic state of the **agent** (e.g., learning algorithm),
- ▶ can in principle be reduced on the basis of additional information (e.g., training data).

Aleatoric versus epistemic uncertainty



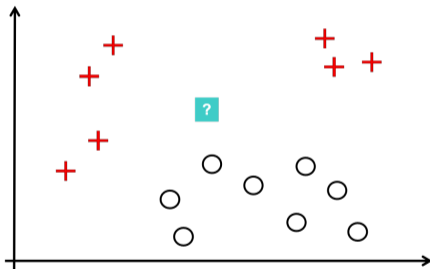
"Not knowing the chance of mutually exclusive events and knowing the chance to be equal are two quite different states of knowledge"

Ronald Fisher (1890-1962)



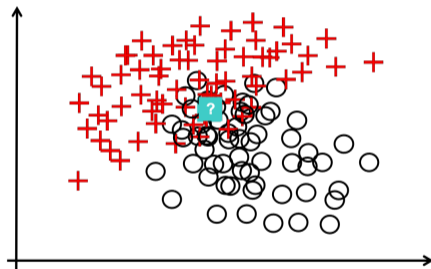
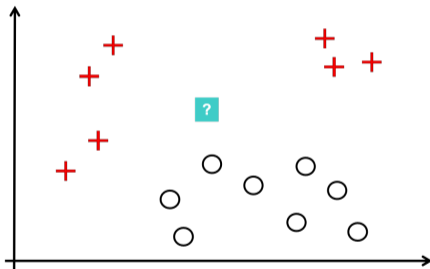
Aleatoric versus epistemic uncertainty in ML

- Both types of uncertainty also play an important role in ML, where the learner's state of knowledge strongly depends on the amount of data seen so far ...



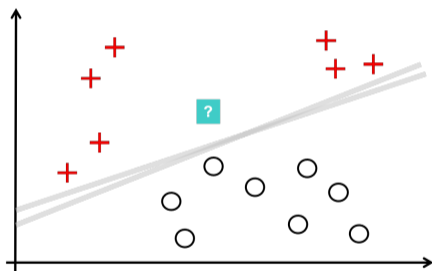
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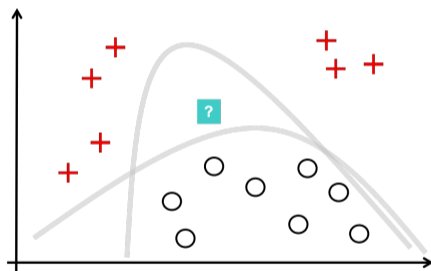


Aleatoric versus epistemic uncertainty in ML

- ... but also on the underlying model assumptions:



strong prior



weaker prior

Uncertainty about (aleatoric) uncertainty

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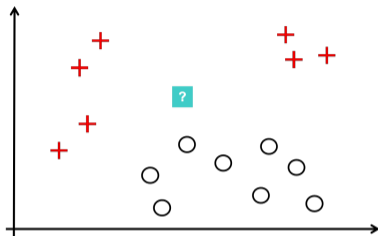
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- **Predict the next number:** 116, 304, 194, 341, 224, 654, 609, 625, 533, 91, 205, 35, 527, 611, 128, 235, 348, 912, 582, 52, 672, 20, 856, 904, 628, 273, 615, 105, 610, 862, 384, 705, 73, 794, 775, 156, ??

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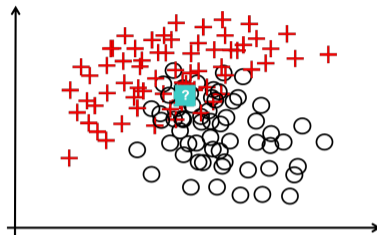
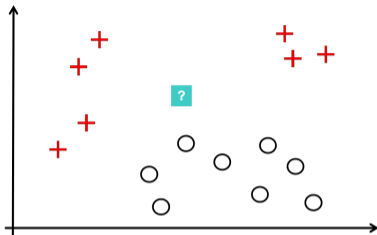
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$$x \leftarrow x \times 237 \bmod 971$$

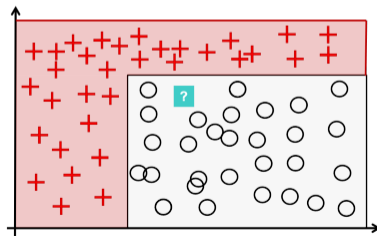
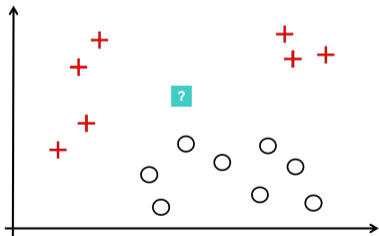
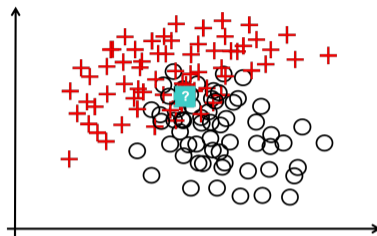
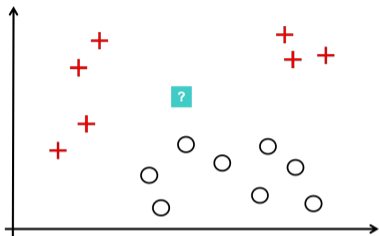
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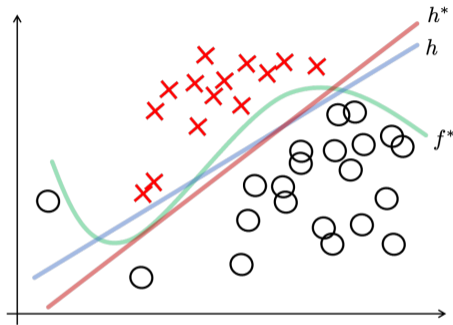
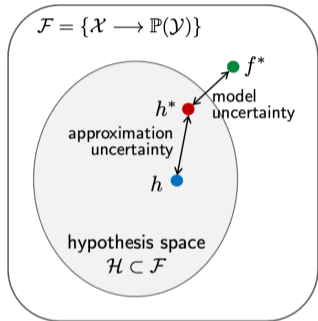
Uncertainty about (aleatoric) uncertainty



Uncertainty about (aleatoric) uncertainty



Sources of uncertainty



$$f^* = \arg \min_{f \in \mathcal{F}} \mathbb{E}_{(\mathbf{x}, y) \sim P} \ell(y, f(\mathbf{x}))$$

$$h^* = \arg \min_{h \in \mathcal{H}} \mathbb{E}_{(\mathbf{x}, y) \sim P} \ell(y, h(\mathbf{x}))$$

$$h^* = \arg \min_{h \in \mathcal{H}} \sum_{i=1}^N \ell(y_i, h(\mathbf{x}_i))$$

Agenda

1. Aleatoric and epistemic uncertainty
2. **Learning uncertainty-aware predictors**
3. Uncertainty quantification
4. Summary and outlook

Predictive uncertainty

Predictive uncertainty

- We assume a standard setting of **supervised learning** and are mainly interested in (per-instance) **predictive uncertainty**, i.e., the uncertainty in a prediction

$$\hat{y} = h(\mathbf{x})$$

produced for a query instance \mathbf{x} , where h has been learned on training data \mathcal{D} .

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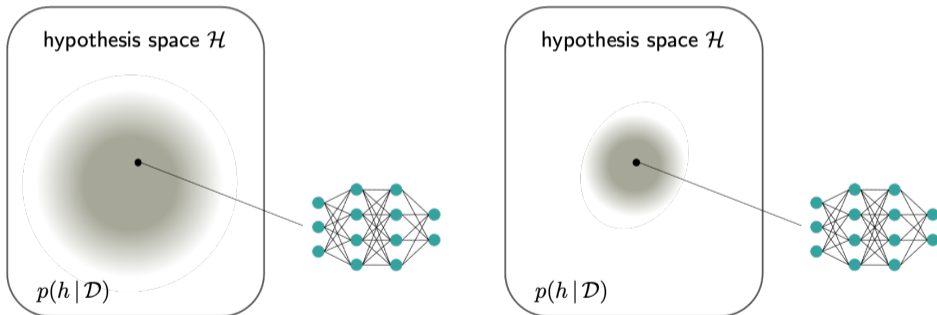
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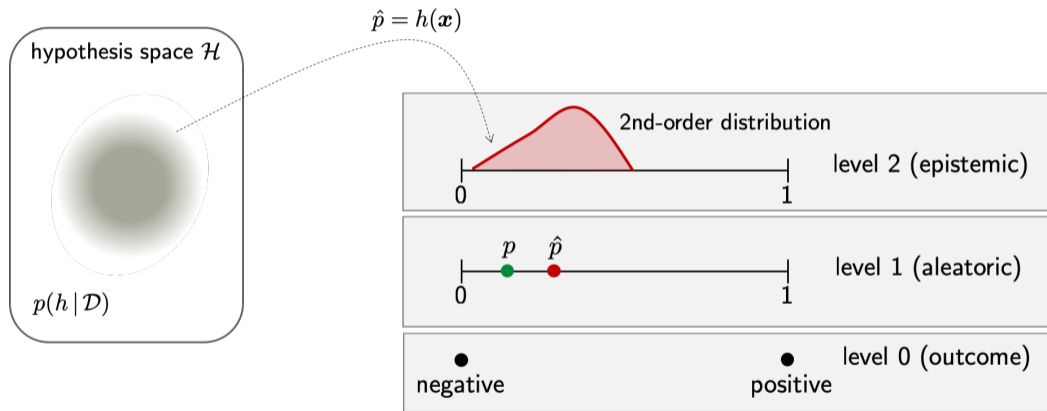
- Various **approaches** have been proposed in the literature:
 - ▶ Capture model uncertainty, translate into predictive uncertainty
 - ▶ Validation and self-assessment
 - ▶ Direct uncertainty prediction

The Bayesian approach

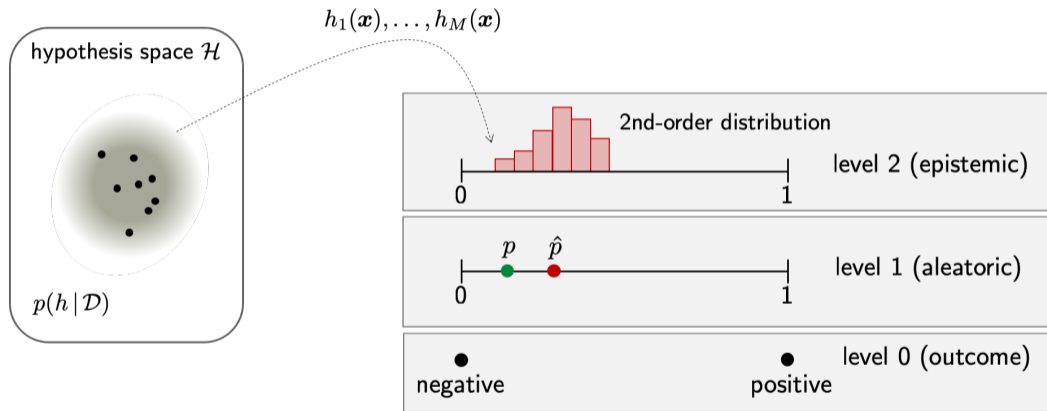
- A Bayesian learner maintains a probability distribution over the hypothesis space.
- The less concentrated that distribution, the higher the learner's epistemic uncertainty.



Posterior predictive distribution



Ensemble methods



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Validation and self-assessment

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- In addition to learning a predictor h on \mathcal{X} , the learner also figures out how that predictor performs on out-of-sample data.



What can be guaranteed for $h(x)$?
How to correct $h(x)$ to make it reliable?

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- Yet, this is a **global** performance measure, not **per-instance**.

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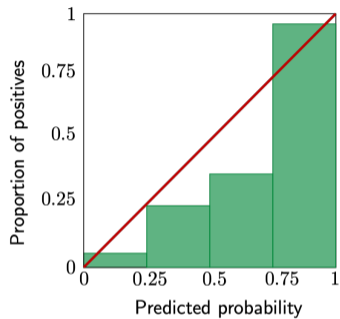
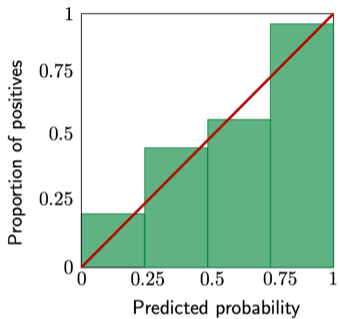
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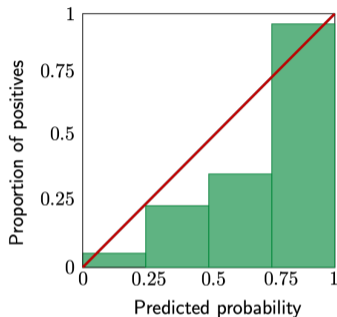
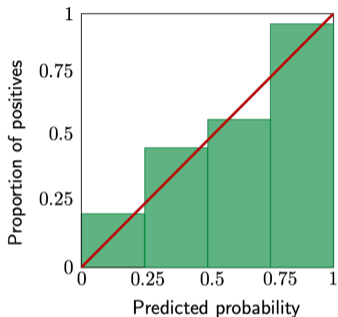
What can be guaranteed for $h(\mathbf{x})$?
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- Example: Estimation of **error rate** via (cross-)validation.
- Yet, this is a **global** performance measure, not **per-instance**.
- Per-instance uncertainty estimation appears to be difficult and indeed has theoretical limits (Barber *et al.*, 2021).

Calibration

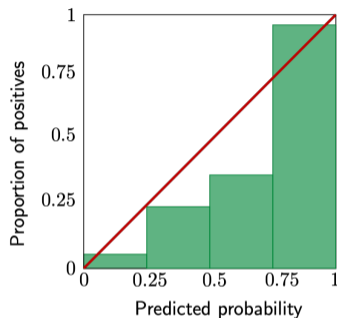
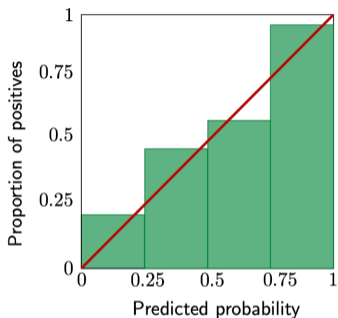


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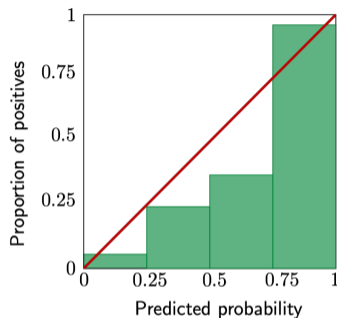
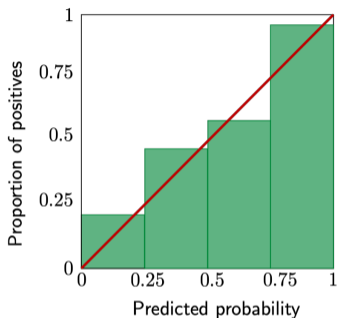
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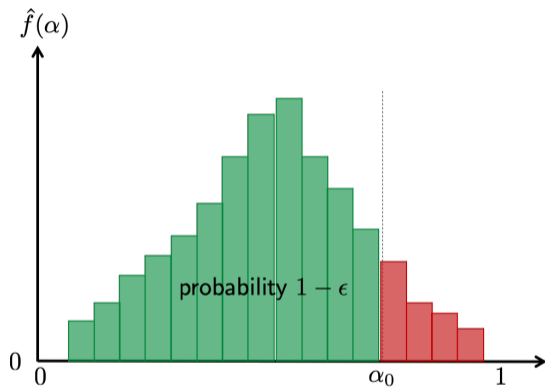
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- **Grouping** of instances with same score (predicted probability), needed to construct frequentist corrections of level-1 predictions based on level-0 data.

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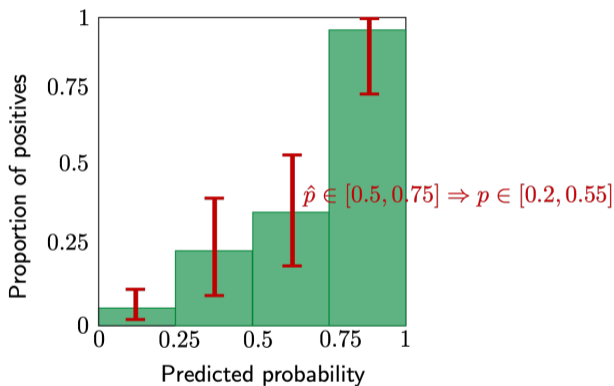
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- **Grouping** of instances with same score (predicted probability), needed to construct frequentist corrections of level-1 predictions based on level-0 data.
- A calibrator is a **one-dimensional** function, hence easier to learn.

Conformal prediction



- A **conformal predictor** uses calibration data to learn rules such as: With high probability, true outcomes have a nonconformity of at most α_0 .
- This allows for constructing non-trivial yet valid **prediction sets**.

Level-2 predictions



- Previous approaches refer to level-1 uncertainty, though level-2 estimation is in principle also possible (e.g., Venn predictors)

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- For example, Lahlou *et al.* (2021) train an **error predictor** on validation data, which can be used to estimate epistemic uncertainty in terms of pointwise (excess) prediction error

$$\mathcal{E}(\hat{h}, \mathbf{x}) = \left(\hat{h}(\mathbf{x}) - f^*(\mathbf{x})\right)^2.$$

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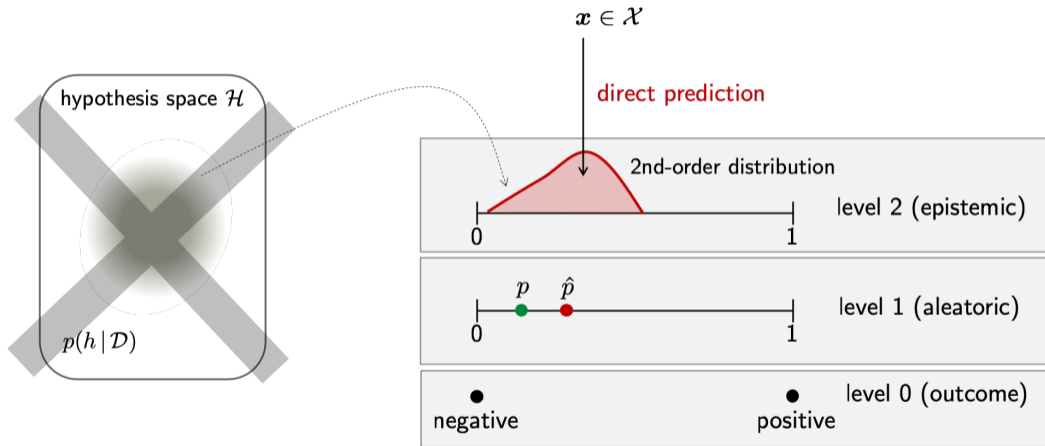
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- Yet, learning such a predictor appears to be difficult (and also includes learning of $f^*(\mathbf{x})$ or knowledge thereof).
- Besides, one may question the definition of **uncertainty** in terms of **loss**.

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Direct prediction



Direct (epistemic) uncertainty prediction

- Given training data $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^N \subset \mathcal{X} \times \mathcal{Y}$, can we train a predictor

$$\hat{h} : \mathcal{X} \longrightarrow \mathbb{P}(\mathbb{P}(\mathcal{Y}))$$

via (variants of) **empirical risk minimisation** (ERM), i.e.,

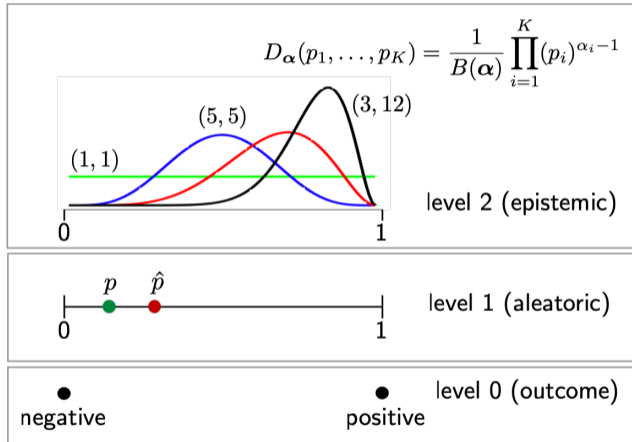
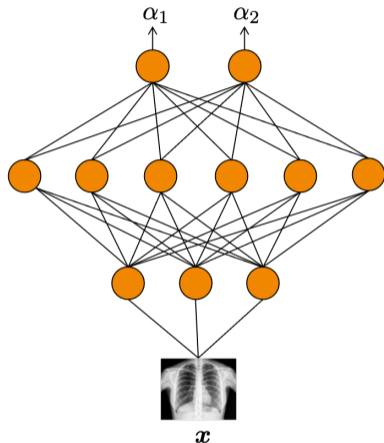
$$\hat{h} = \arg \min_h \sum_{i=1}^N \ell_2 \left(\hat{h}(\mathbf{x}_i), y_i \right),$$

with a suitable **level-2 loss function**

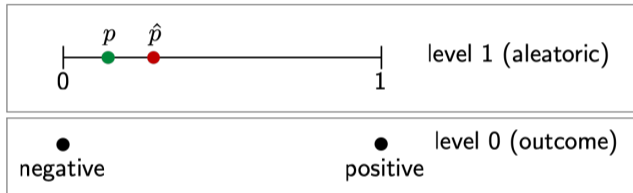
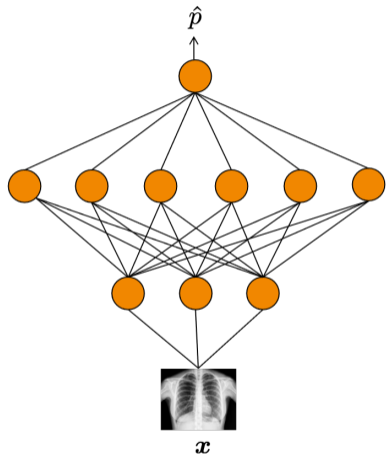
$$\ell_2 : \mathbb{P}(\mathbb{P}(\mathcal{Y})) \times \mathcal{Y} \longrightarrow \mathbb{R},$$

such that the predictor represents its epistemic uncertainty in a faithful way?

Example: predicting a Dirichlet distribution



The case of level-1 predictions



Direct (epistemic) uncertainty prediction

- Training a probabilistic predictor via **empirical risk minimisation**, i.e.,

$$\hat{h} = \arg \min_h \sum_{i=1}^N \ell_1 \left(\hat{h}(\mathbf{x}_i), y_i \right) ,$$

yields good (unbiased) predictors if ℓ_1 is a (strictly) **proper scoring rule**, which incentivises the learner to predict the true $p(y | \mathbf{x})$.

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- A loss function $\ell_1 : \mathbb{P}(\mathcal{Y}) \times \mathcal{Y} \rightarrow \mathbb{R}$ is a proper scoring rule if the expected loss minimiser coincides with the true probability \mathbf{p} :

$$\mathbf{p} = \arg \min_{\hat{\mathbf{p}}} \mathbb{E}_{Y \sim \mathbf{p}} \ell_1(\hat{\mathbf{p}}, Y)$$

A scoring rule is **strictly proper** if the minimiser is unique.

Direct epistemic uncertainty prediction

- Several authors proposed a **level-2 loss** of the form

$$l_2(Q, y) = \mathbb{E}_{P \sim Q} l_1(P, y),$$

where Q is the level-2 prediction for a query instance \mathbf{x} .

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- Thus, an individual prediction Q is penalised in terms of the **expected level-1 loss**, with the expectation taken over the realisations of P .
- Examples of level-1 losses include cross entropy (Charpentier *et al.*, 2020) and Brier score (Sensoy *et al.*, 2018).
- Besides, a **regularised version** has been proposed:

$$\ell_2(Q, y) = \mathbb{E}_{P \sim Q} \ell_1(P, y) + \lambda d_{KL}(Q, Q_0)$$

Appropriate level-2 losses

- Informally, we define a level-2 loss function ℓ_2 as **appropriate** if the following holds for the empirical loss minimiser

$$Q^{(N)} = \arg \min_Q \frac{1}{N} \sum_{n=1}^N \ell_2 \left(Q, y^{(n)} \right)$$

on any i.i.d. observational data sequence $y^{(1)}, y^{(2)}, \dots$ with $y^{(i)} \sim P^*$:

- (A1) The learner's **uncertainty gradually decreases** (in expectation) with increasing sample size N , in terms of a suitable uncertainty measure U .
- (A2) In the limit $N \rightarrow \infty$, all **epistemic uncertainty disappears** and $Q^{(N)} \rightarrow \delta_{P^*}$.

A negative result

- We formally proved that a loss minimisation approach using a level-2 loss as specified above does not lead to an appropriate level-2 loss (Bengs *et al.*, 2022).

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- Moreover, the results do not depend on the underlying uncertainty measure U , as long as U is not constant, maximal for the uniform distribution and minimal for Dirac measures.
- The results reveal that the quality of a (level-2) prediction Q cannot be judged solely in the context of (level-0) observations y .

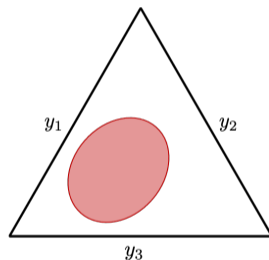
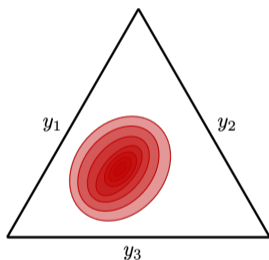
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4. Summary and outlook

Uncertainty quantification

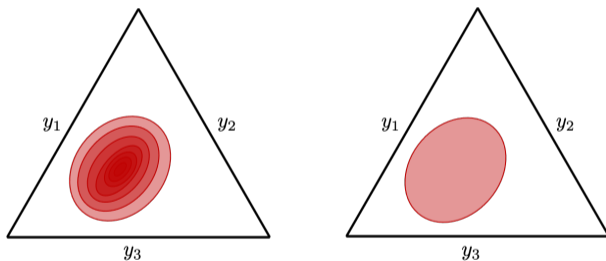
Uncertainty quantification

- Given a prediction $h(\mathbf{x})$ in the form of a second-order distribution or a credal set, how to quantify the **total uncertainty** in that prediction in terms of a single number?



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- We may also seek a **decomposition** into an aleatoric and an epistemic part:

$$TU = AU + EU$$

Uncertainty quantification

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- One idea is to quantify the different types of uncertainty in terms of

- ▶ **Shannon entropy**

$$H[Y] = - \sum_{y \in \mathcal{Y}} \mathbf{p}(y) \log_2 \mathbf{p}(y),$$

- ▶ **conditional entropy**

$$H[Y | P] = - \int Q(p | \mathcal{D}) \left(\sum_{y \in \mathcal{Y}} \mathbf{p}(y | p) \log_2 \mathbf{p}(y | p) \right) dp,$$

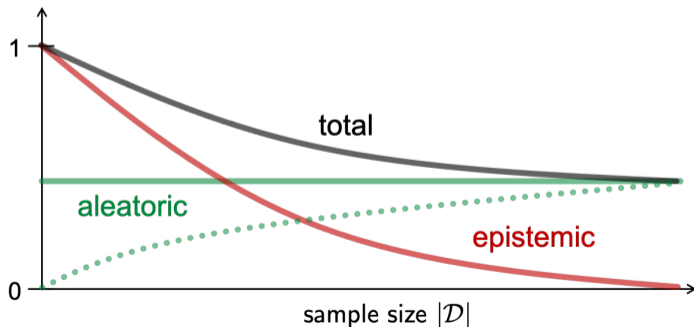
- ▶ and **mutual information**

between outcome Y and (level-1) distribution P (Malinin and Gales, 2018), respectively:

$$\underbrace{H[Y]}_{\text{total uncertainty}} = \underbrace{H[Y | P]}_{\text{aleatoric uncertainty}} + \underbrace{I(Y; P)}_{\text{epistemic uncertainty}}$$

Remarks

- MI actually measures the (average) **divergence** between the candidate (level-1) distributions, so it is rather a measure of **conflict** than **ignorance** (which is difficult to capture in terms of probabilities anyway).
- One may also question the **additive decomposition** $TU = AU + EU$ itself.



Uncertainty of credal sets

Uncertainty of credal sets

- Uncertainty measures U for credal sets have been studied **axiomatically**:
 - A1 **Non-negativity, range**: U is non-negative and upper-bounded by some value $r \in \mathbb{R}$, for example $r = \log(K)$, which is assumed for $Q = \Delta_K$ (the case of complete ignorance).
 - A2 **Continuity**: U is a continuous functional.
 - A3 **Monotonicity**: If $Q \subseteq Q'$ for credal sets Q, Q' , then $U(Q) \leq U(Q')$.
 - A4 **Probability consistency**: U reduces to standard Shannon entropy in the case where Q reduces to a single probability distribution.
 - A5 **Sub-additivity**: For a (joint) credal set Q on a product space $\mathcal{Y}' \times \mathcal{Y}''$ with marginals Q' resp. Q'' ,
$$U(Q) \leq U(Q') + U(Q'').$$
 - A6 **Additivity**: The last inequality is an equality in the case where Q' and Q'' are independent (assuming a suitably defined notion of independence).

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- Although an equally well-justified measure of **aleatoric uncertainty** (conflict) in the form of an extension of Shannon entropy has not been found so far (Klir, 2005), the **lower entropy** is a natural measure of **irreducible uncertainty**:

$$S_*(Q) := \min_{q \in Q} S(q)$$

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- H. *et al.* (2022) provide a **critical discussion** of such decompositions and isolate **potential deficiencies**.

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- In the case of **binary classification**, where a credal prediction is of the form

$$Q_{\alpha,\beta} = \{ \text{Bern}(p) \mid \alpha \leq p \leq \beta \},$$

the measure is given as follows:

$$\text{TP}(\alpha, \beta) = \underbrace{\min(1 - \alpha, \beta)}_{\text{total}} = \underbrace{\min(\alpha, 1 - \beta)}_{\text{aleatoric}} + \underbrace{(\beta - \alpha)}_{\text{epistemic}}$$

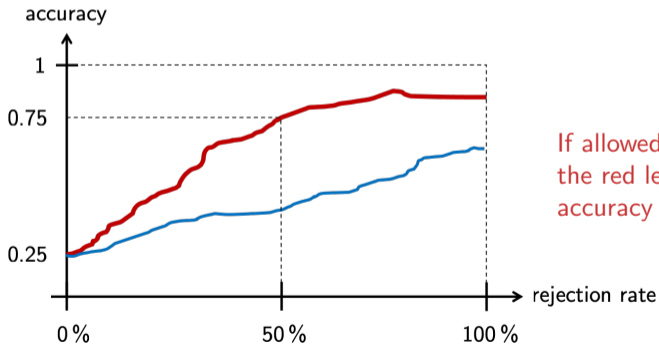
Empirical evaluation

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- **Ensemble-based construction** of credal predictions.
- **Accuracy-rejection curves**: Allow the learner to reject the r % presumably most uncertain test cases and measure accuracy on the remaining ones.



If allowed to reject 50 % of the cases, the red learner manages to increase accuracy from 0.25 to 0.75.

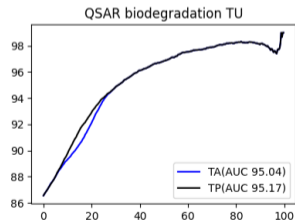
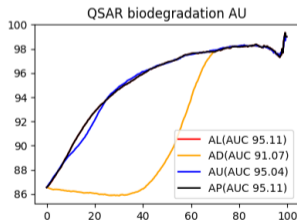
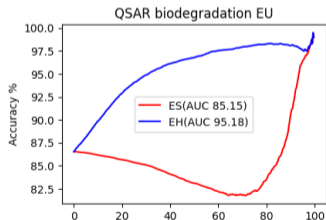
Results

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- Empirical results match with theory: Formally justified measures show strong performance, whereas the “derived” measures perform very poorly.
- Newly proposed measure yields the only decomposition of total into aleatoric and epistemic uncertainty, such that all three measures produce meaningful results.



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- **Distinguishing different sources and types of uncertainty** is useful, though it seems that epistemic uncertainty hard to represent in an objective way (depends on prior, regularisation, incentive, etc.).
- **Quantifying predictive uncertainty** in a theoretically sound manner, and disentangling total into aleatoric and epistemic uncertainty, is difficult, too.

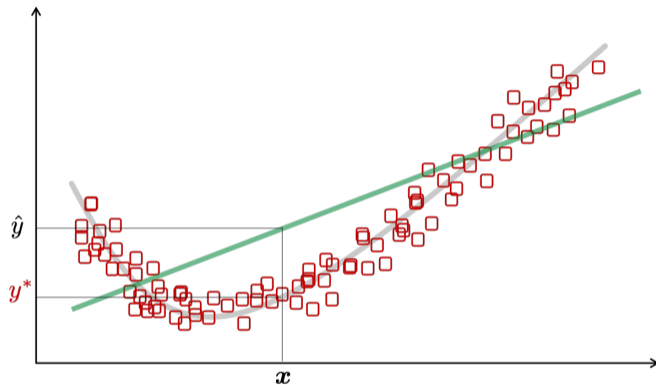
Summary and Outlook

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- Usefulness of **generalized uncertainty calculi**?

References

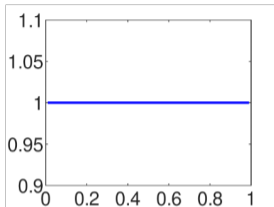
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Model misspecification

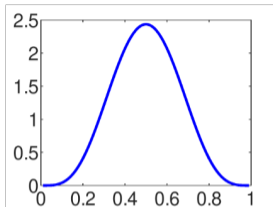


What uncertainty should the learner report at x ?

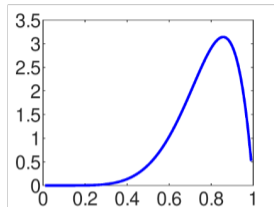
Example: level-2 distributions over Bernoulli



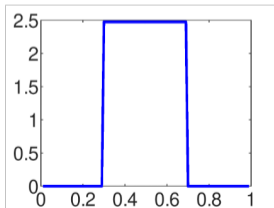
TU = 1.00, AU = 0.73, EU = 0.27



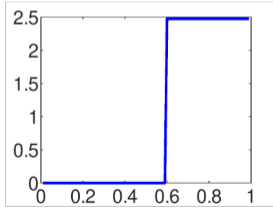
TU = 1.00, AU = 0.93, EU = 0.07



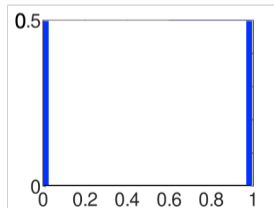
TU = 0.76, AU = 0.69, EU = 0.07



TU = 1.00, AU = 0.96, EU = 0.04



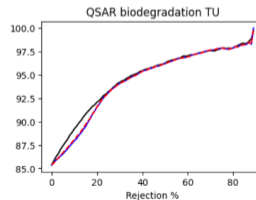
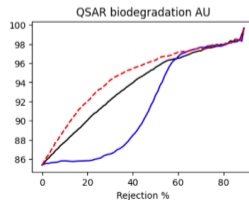
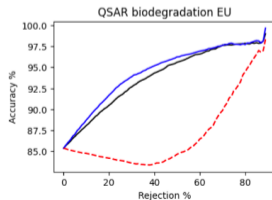
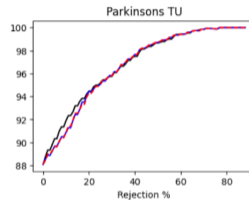
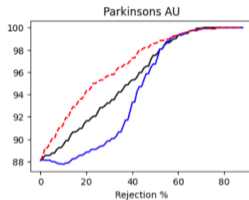
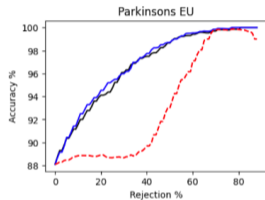
TU = 0.73, AU = 0.67, EU = 0.07



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Evaluation: accuracy-rejection curves

- Reject test instances for which (total, aleatoric, epistemic) uncertainty exceeds a certain threshold, measure accuracy on the remaining ones.



A negative result

■ **Theorem 1.** If $\ell_1 : \mathbb{P}(\mathcal{Y}) \times \mathcal{Y} \rightarrow \mathbb{R}$ is such that

$$\ell_1(\mathbb{E}_{\theta \sim Q}[\theta], y) \leq \mathbb{E}_{\theta \sim Q}[\ell_1(\theta, y)]$$

for all $y \in \mathcal{Y}$, then $\ell_2(Q, y) = \mathbb{E}_{\theta \sim Q}[\ell_1(\theta, y)]$ violates A1.

- ▶ Condition on ℓ_1 is fulfilled if ℓ_1 is convex (in the first argument)
- ▶ Includes Brier score and cross-entropy, which are (strictly) convex
- ▶ Proof reveals that \hat{Q} is always a point-mass on $\mathbb{P}(\mathcal{Y})$ (i.e., a level-1 prediction)

A negative result

- **Theorem 2.** If $\ell_1 : \mathbb{P}(\mathcal{Y}) \times \mathcal{Y} \rightarrow \mathbb{R}$ is strictly convex in its first argument, then there exists $\bar{\lambda} > 0$ such that

$$\ell_2(Q, y) = \mathbb{E}_{\boldsymbol{\theta} \sim Q} [\ell_1(\boldsymbol{\theta}, y)] + \lambda \cdot \text{KL} [Q, \text{Unif}(\mathbb{P}(\mathcal{Y}))]$$

violates A1 for all $\lambda < \bar{\lambda}$.

A negative result

- **Theorem 3.** If $\ell_1 : \mathbb{P}(\mathcal{Y}) \times \mathcal{Y} \rightarrow \mathbb{R}$ is
- (i) strictly proper,
 - (ii) locally Lipschitz (in the first argument),
- then there exists $\underline{\lambda} > 0$ such that

$$\ell_2(Q, y) = \mathbb{E}_{\theta \sim Q} [\ell_1(\theta, y)] + \lambda \cdot \text{KL} [Q, \text{Unif}(\mathbb{P}(\mathcal{Y}))]$$

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- Brier score and cross-entropy fulfill both (i) and (ii).

The need for assumptions

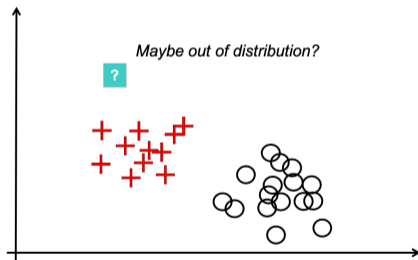
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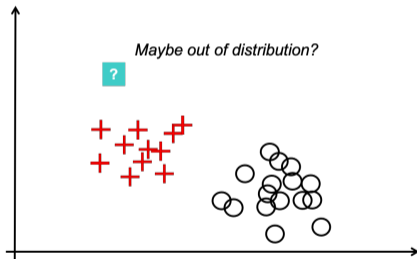
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- Here, one might be quite sure about the class of the query under standard assumptions of binary classification, but much less so in a setting of **novelty detection**, where new classes may emerge.

The Dirichlet distribution

- A **Dirichlet distribution** $\text{Dir}(\alpha)$ is specified by means of $K \geq 2$ positive real-valued parameters, i.e., a vector $\alpha = (\alpha_1, \dots, \alpha_K) \in \mathbb{R}_+^K$.

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- The probability density function is defined on the K simplex

$$\Delta_K = \left\{ \boldsymbol{\theta} = (\theta_1, \dots, \theta_K)^\top \mid \theta_1, \dots, \theta_K \geq 0, \sum_{k=1}^K \theta_k = 1 \right\}$$

and given as follows:

$$p(\boldsymbol{\theta} \mid \boldsymbol{\alpha}) = p(\theta_1, \dots, \theta_K \mid \boldsymbol{\alpha}) = \frac{1}{\mathbb{B}(\boldsymbol{\alpha})} \prod_{k=1}^K \theta_k^{\alpha_k - 1},$$

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- In Bayesian statistics, the Dirichlet distribution is commonly used as the conjugate prior of the **multinomial distribution**.